

Experimental tests on FOWT models

Structures / Modelling and Design Tools

Control

 Non directly applicable from onshore

- Instability issues
- Cycle limits motion

Aerodynamics

- Turbulence
- Aero-structure
- Unsteady

Overall dynamics

- Integrated tools
- Simplified models for control and design

Hydrodynamics

- 2nd order important for lighter structures: sum and diff QTFs
- Multi-directional

Blades: large deformations

- Materials
- Fatigue design

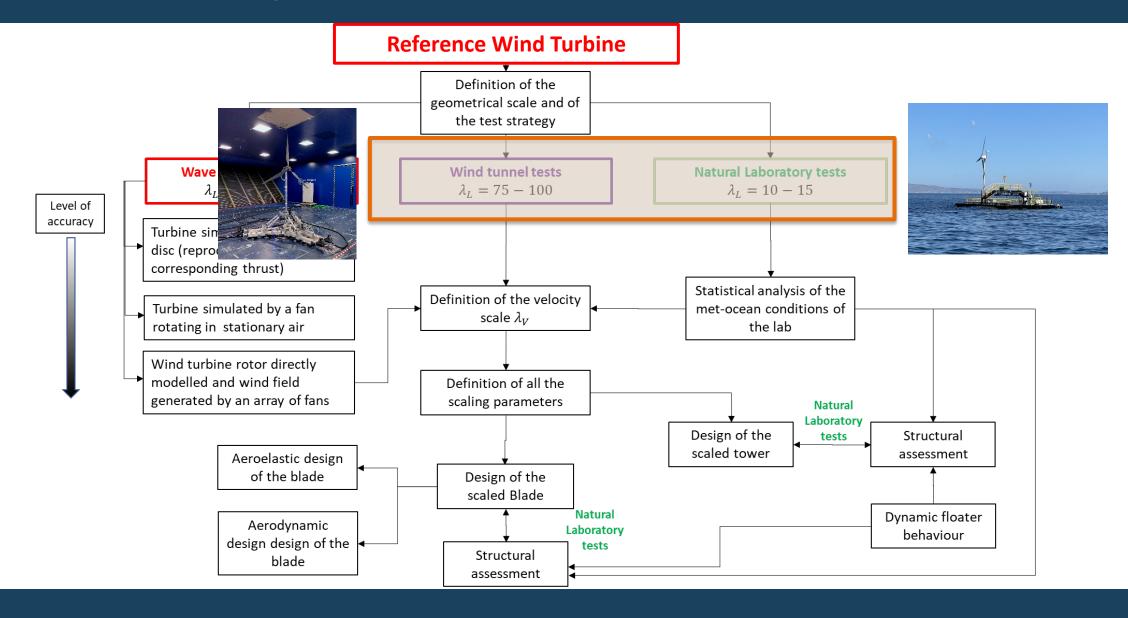
Drivetrains

- Hub's accelerations
- Weight
- Fatigue durability

Tower-Platform connection

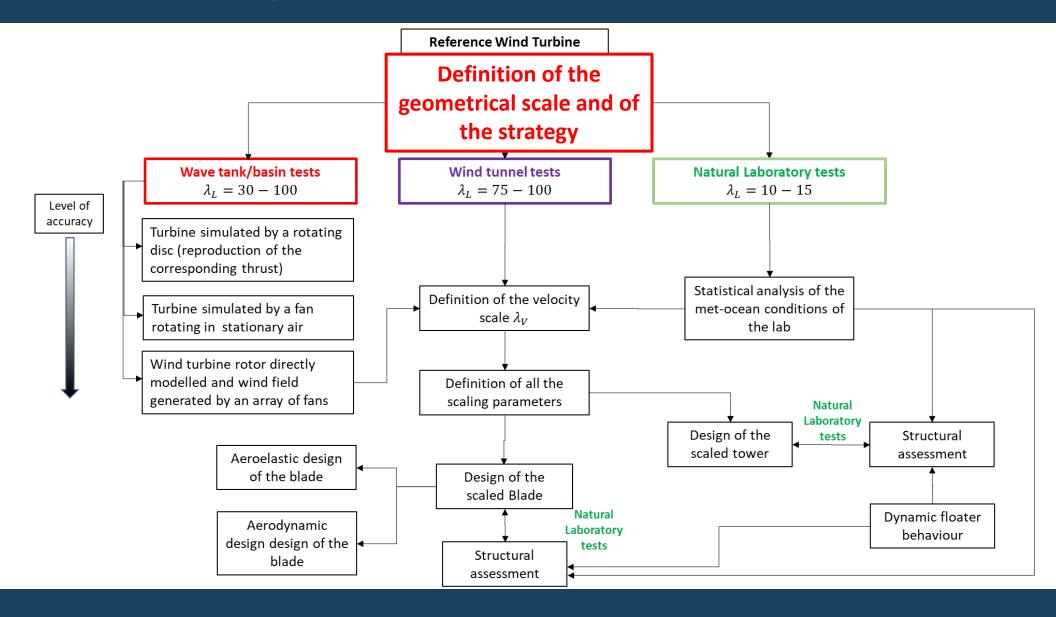
Platform design: optimization for lighter structures w.r.t O&G







Value	Units
4	m/s
25	m/s
11.4	m/s
178.3	m
5.6	m
119	m
6	rpm
9.6	rpm
228	t
446	t
628.4	t
1400	kN
0.25	Hz
0.61	Hz
0.93	Hz
	4 25 11.4 178.3 5.6 119 6 9.6 228 446 628.4 1400 0.25 0.61



Wind tunnel tests

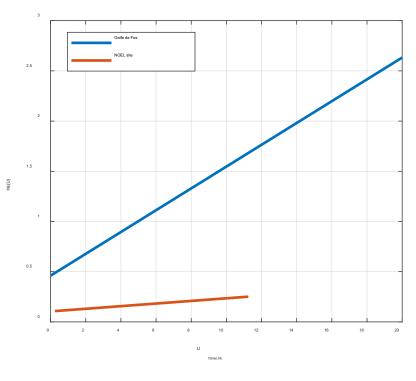
Maximum model dimensions are limited by WT section height



Maximum turbine model diameter: 2.0-2.6 m

Natural Laboratory tests

Evaluation of the significant wave height



NOEL: typical scale factor: 1:10- 1:20

Froude scaling

$$Fr = \frac{U}{\sqrt{gL}} \implies \lambda_V = \sqrt{\lambda_L}$$

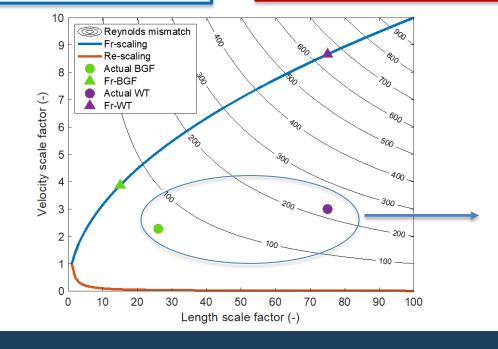
for reproducing the wave and gravity forces

Reynolds scaling

$$Re = \frac{UD}{v} \quad \Longrightarrow \quad \lambda_V = \frac{1}{\lambda_L}$$

for reproducing blade aerodynamics

It is impossible to simultaneously match Reynolds and Froude numbers



a compromise has to be reached considering other factors

Wind tunnel tests

Velocity ratio is limited by the wind tunnel velocity range:

Polimi Wind Tunnel (WT) boundary layer test section:

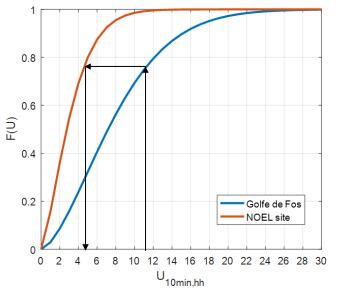
- Available test wind speed=3-15 m/s
- DTU 10 MW operational range=4-25 m/s
- Preferable rated velocity for the model:
- V_{model} rated=4.6-8 m/s

$$\lambda_V = \frac{U_{Real}}{U_{model}} = 1.25 - 2.5$$

The length and velocity scale factors can set one independently from the other: in hybrid/HIL experiments, it is possible to simulate FOWT dynamics without having to rely on Froude similitude

Natural Laboratory tests

A statistical approach must be used



Wind speed cumulative probability

The turbine structure (except the rotor) can be scaled according to Froude law and the performances (rotor dimension included) can be scaled according to a generic scale

Symbol	Expression
λ_L	_
λ_v	-
λ_a	${\lambda_v}^2/\lambda_L$
λ_f	λ_v/λ_L
λ_M	${\lambda_L}^3$
λ_J	${\lambda_L}^5$
λ_F	$\lambda_L^2 \lambda_v^2$
λ_P	$\lambda_L {\lambda_{ u}}^3$
λ_{Re}	$\lambda_L\lambda_{\mathcal{v}}$
λ_{Fr}	$\lambda_v/{\lambda_L}^{0.5}$
	$egin{array}{c} \lambda_L \ \lambda_v \ \lambda_a \ \lambda_f \ \lambda_M \ \lambda_J \ \lambda_F \ \lambda_{Re} \end{array}$

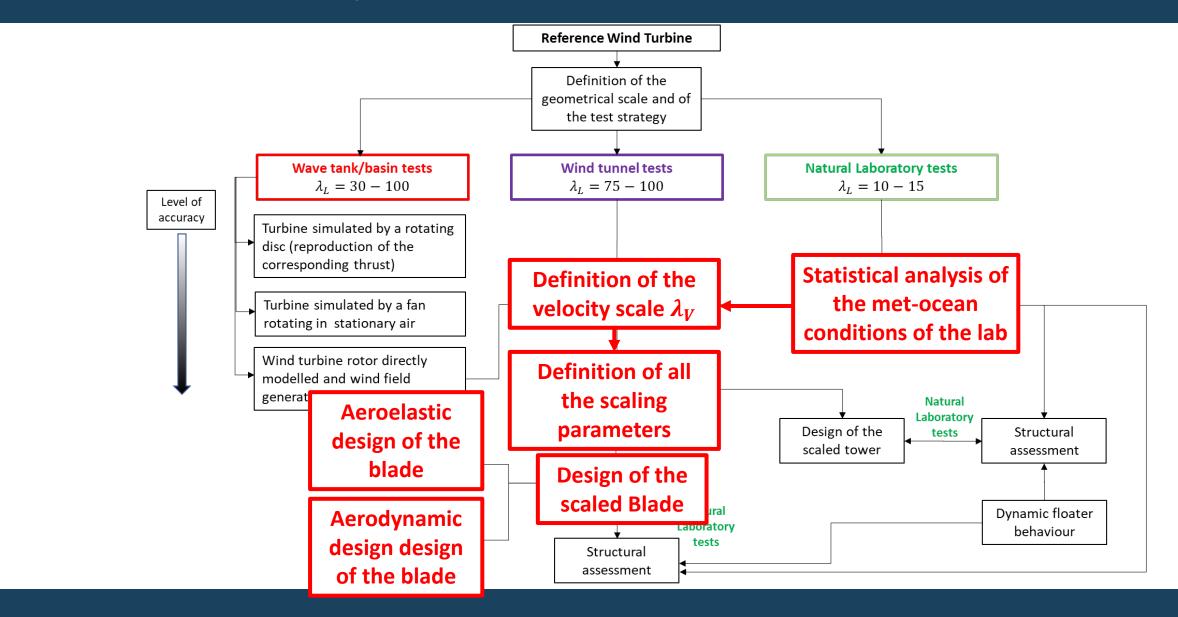
Wind tunnel model

Scale factor	Value
Length	75
Velocity	3
Frequency	1/25
Mass	421,875
Force	50,625
Re num. ratio	225
Fr num. ratio	26

Natural Laboratory model

Wind Turbine sub- system	Scale Factor	Value
	Length	15
	Frequency	0.258
Structure (Fraude)	Mass	3375
Structure (Froude)	Inertia	759,375
	Force	3375 ¹
	Re num.	58
	Length	26
	Velocity	2.28
	Frequency	0.088
Rotor (non-Froude)	Inertia	11,881,376
	Force	3514.12 ¹
	Power	8012.19
	Re num. ratio	59
	Fr num. ratio	12

Workflow for the design of scaled wind turbine



Main requirements:

- ☐ match the rotor thrust force

responsible for the coupled rotor-platform dynamics

- ☐ reproduce the power as good as possible and
- ☐ match the first flap-wise bending mode.

Full Scale RWT

- Chord
- **Twist**
- (Relative thickness)
- Blade axial load

Model airfoil

- ➤ Airfoil Type
- ➤ Distribution along blade

Scaling

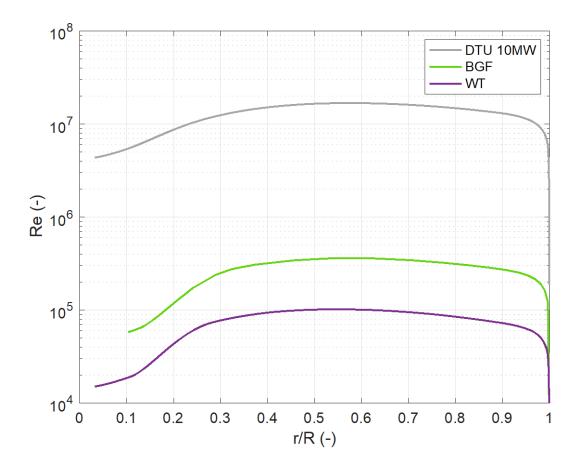
- > Length scale factor
- > Velocity scale factor

Other constraints

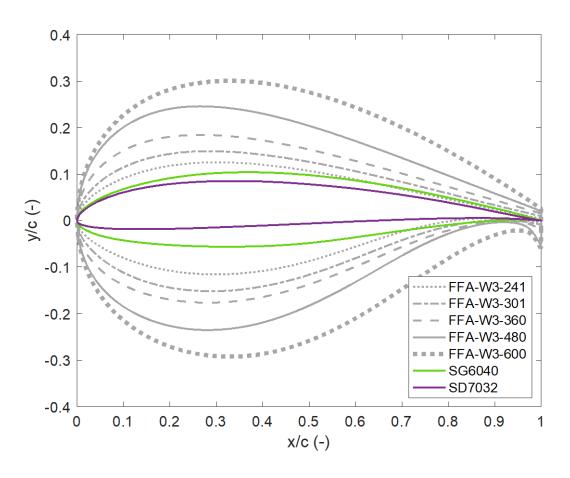
➤ Hub diameter



Reynolds number along the chord: models compared with the RWT



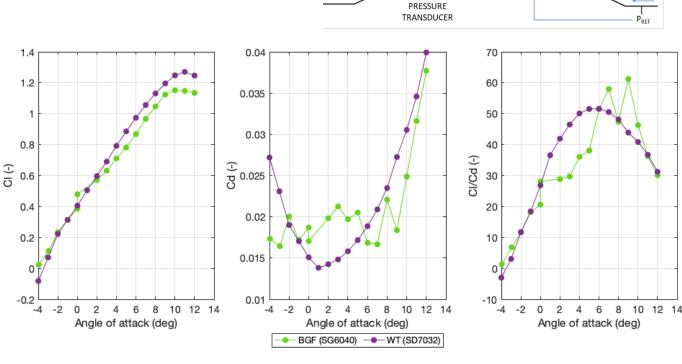




Tests performed on 2D profile permit to verify the aerodynamic coefficients provided by literature









TRANSDUCER

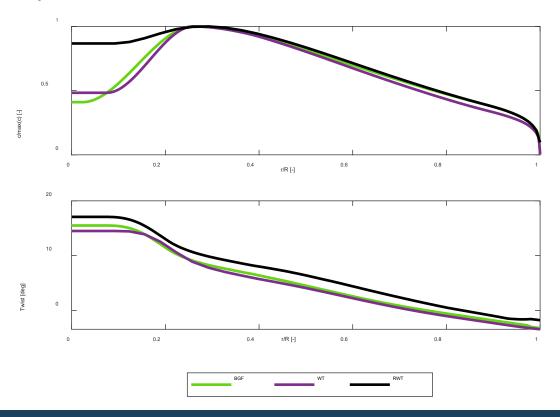
TURBULENCE SCREEN

GOAL OF THE 3D DESIGN:



preserve the thrust imposing kinematic similarity

At every iteration the optimal chord and twist distributions are computed to match the thrust force on the rotor.





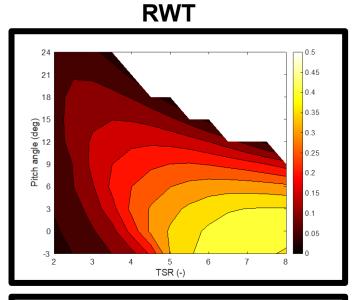
$$TSR_{R} = \frac{\Omega_{R}R_{R}}{V_{R}} = \frac{\Omega_{m}R_{m}}{V_{m}} = TSR_{m}$$

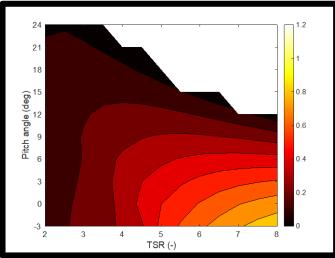
$$\lambda_{\Omega} = \frac{\Omega_{R}}{\Omega_{M}} = \frac{R_{M}V_{R}}{R_{R}V_{M}} = \frac{\lambda_{U}}{\lambda_{L}}$$

TSR: Tip Speed Ratio

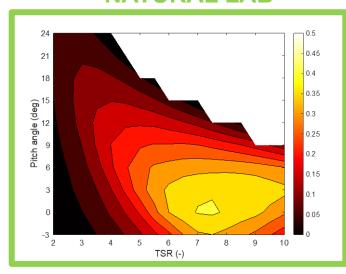


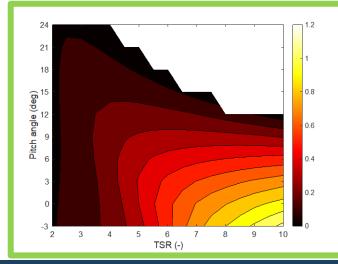
THRUST COEFF.



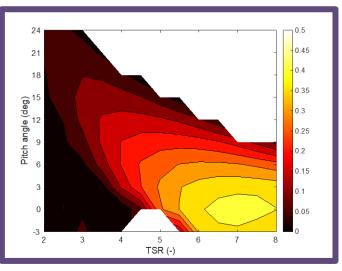


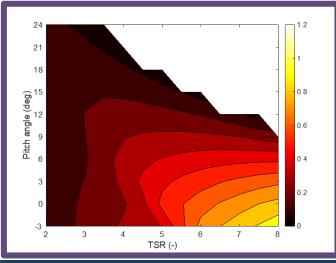
NATURAL LAB





WIND TUNNEL





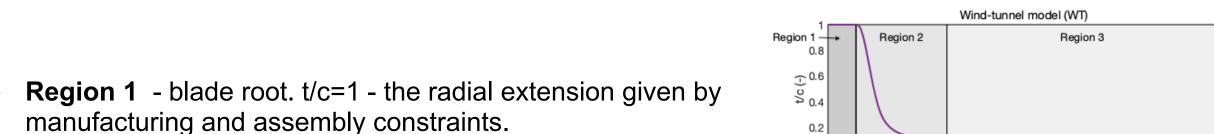
0.9

Main parameters:

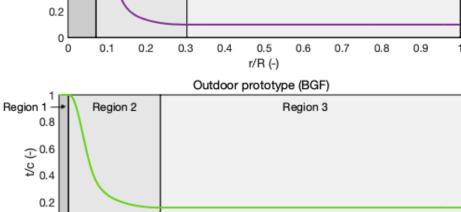
Effects on the Floating structure dynamics

- Mass: match/minimization
- Stiffness

Effects on the flexible dynamics of the rotor



- Region 3 tip region nominal t/c for the selected airfoil.
- Region 2 transition region longer transition ↑ flapwise stiffness ↓ aerodynamic performances.



0.1

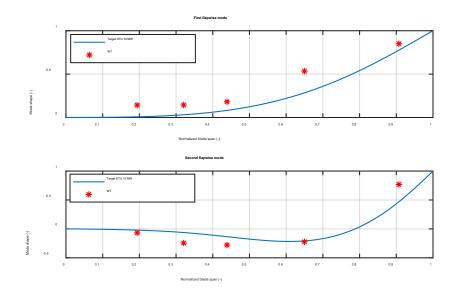
0.2

r/R (-)

Wind tunnel model

Flapwise Mode	Target Frequency (Hz)	WT Model Frequency (Hz)
First	22.87	17.10
Second	65.25	56.40

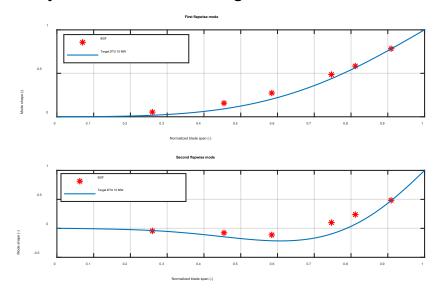
Region 2 was defined in order to optimize the aeroelastic design



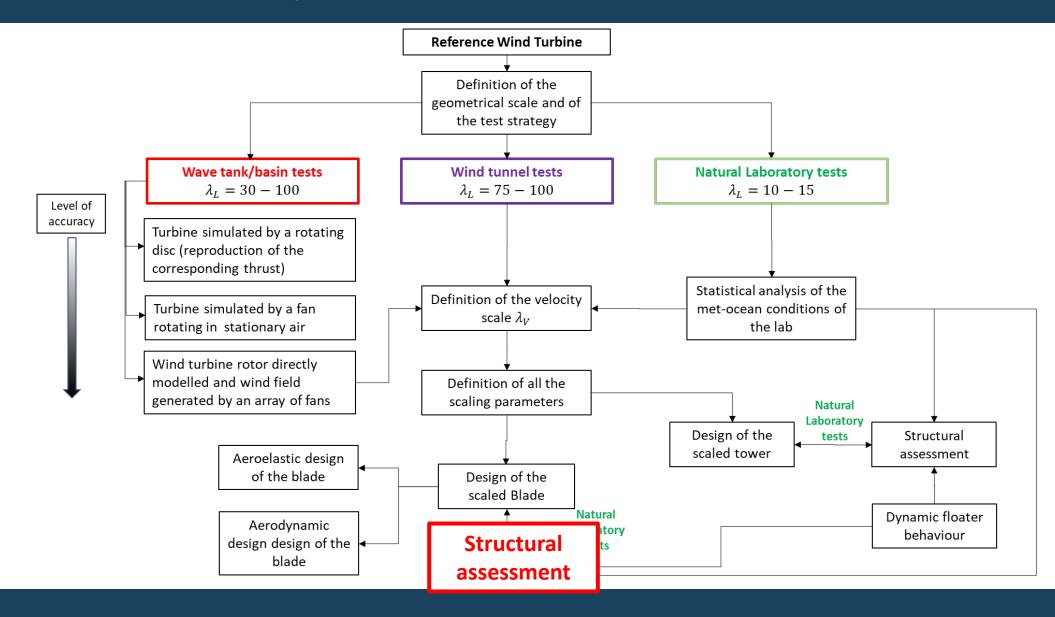
Natural Laboratory model

Flapwise Mode	Target Frequency (Hz)	WT Model Frequency (Hz)
First	2.36	7.82
Second	6.74	19.38

Region 2 was defined in order to have the minimum stiffness permitted by the structural design



Workflow for the design of scaled wind turbine

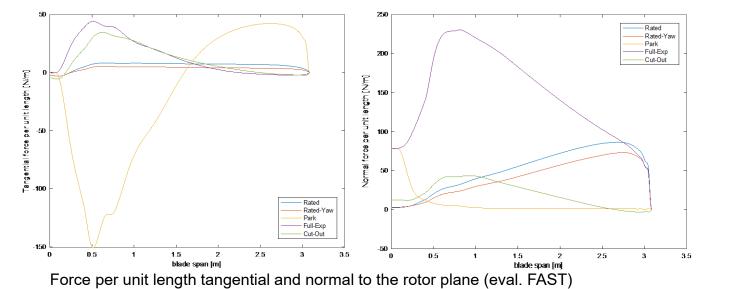


DLCs [IEC61400]

Case Name	U [m/s]	W [rpm]	Blade Pitch [°]	Yaw Angle [°]
Rated	5	101.9	0	0
Rated Yaw	5	101.9	0	30
Park	33	0	90	0
Full Exposure	33	0	0	0
Cut-Out	10.96	109.47	22.67	0



- Rated (5m/s, pitch 0°)
- Rated-Yaw
- Cut-Out
- Full-Exposure (33m/s, pitch 0°)
- Park



Requirements:

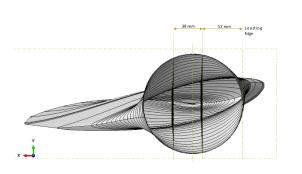
- Static assessment
- 1:15 Mass constraint
- 1st frequency > 3p

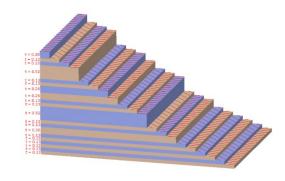
Materials: GFRP

S2-glass UD (0°)

• E-glass FABRIC (±45°)

	Bladespan [m]	Stacking Sequence	Thick [mm]
	0-0.774	3X[±45°]+2X[0°/±45°/0°] _S	3.9
shell	0.774 - 1.666	2X[±45°]+2X[0°/±45°/ <u>0°</u>] _S	3.12
	1.666 - 2.576	2X[±45°]+[±45°/0°/±45°] _S	1.3
External	2.576 - 2.902	2X[±45°]	0.52
	2.902 - 3.086	[±45°]	0.26
sq	0.089 - 0.774	[±45°/±45°/90°/±45°/±45°/90°] _s	3.12
Webs	0.774 - 2.19	[±45°/90°/±45°/±45°/90°/±45°]	1.56





FEA - Abaqus model

Blade mass: 7.317 kg

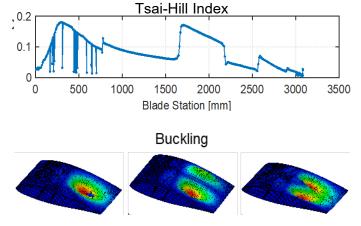
Natural frequencies:

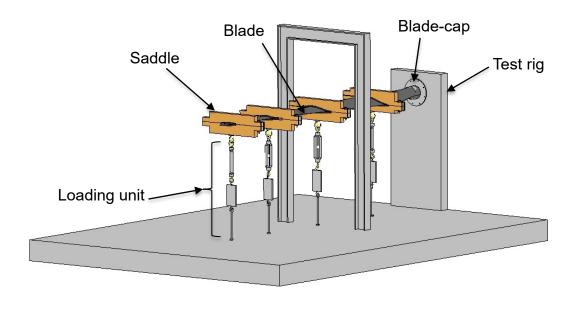
• Mode 1: 9.71 *Hz*

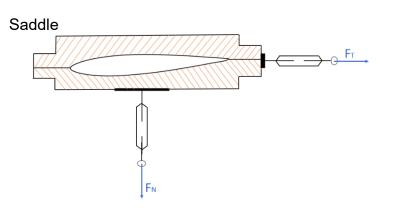
• Mode 2: 23.54 Hz

Assessment performed:

- ✓ Static Analysis
- ✓ Buckling Analsis
- ✓ Tip-Tower Clearance







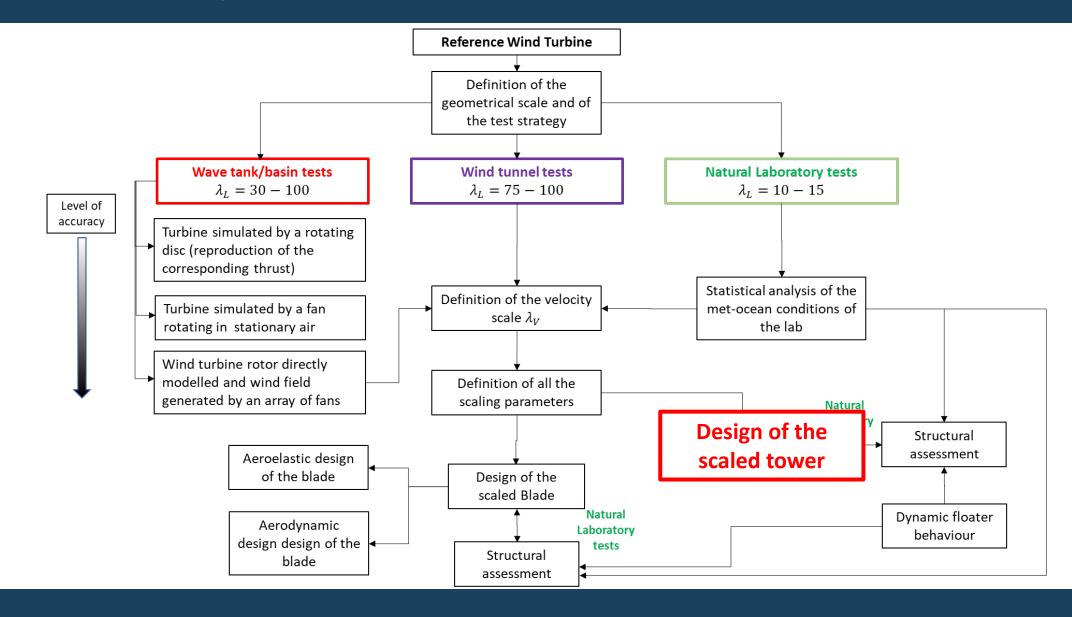
Structural tests:

- 1. FEM validation:
 - Target: verify material properties
 Strategy: reproduction of *bending moment*
- 2. Blade structural assessment:
 Target: verify blade resistance in design conditions
 Strategy: reproduction of *shear stress*
- 3. Blade root to flange connection assessment





Workflow for the design of scaled wind turbine



Structural tower design

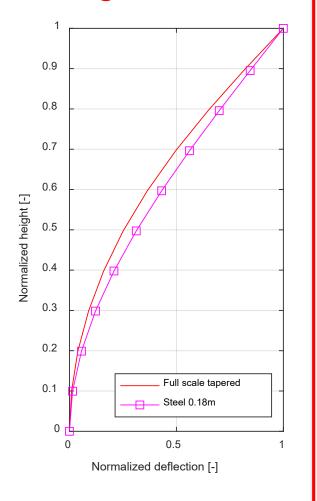
Froude scaling of the aeroelastic tower parameters in order to match f-a and s-s frequencies and modal shape



Scaled distributed stiffness and inertial properties

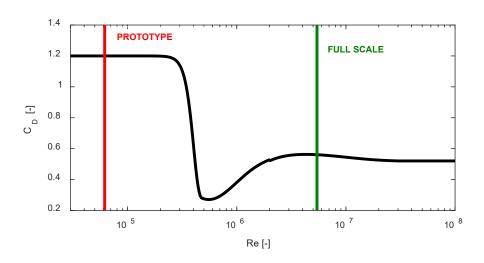
Assessments (for Natural Lab model):

- Tower buckling
- ✓ Top plate connection
- Stress concentration at tower-stiffener interface



Aerodynamic tower design

Lack in Re Number between model and fullscale is expected

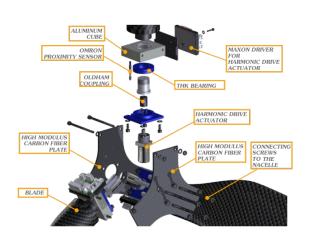


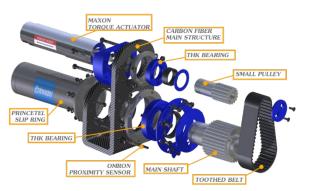
Similar fluid-structure interactions are expected in postcritical and subcritical Re Number range

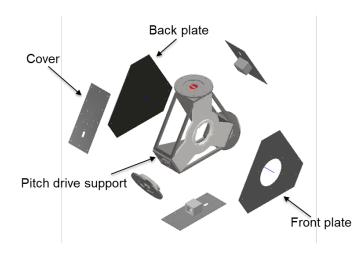
Main requirements:

- Masses properly scaled
- ☐ Hub and Nacelle functionalities properly reproduced

Optimized solutions to obtain the functionalities controlling the masses

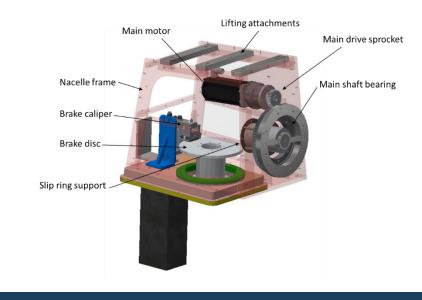






Component	Target [g]	Model [g]
Rotor	540	1270
Nacelle	1535	1057.3

Component	Target [kg]	Model [kg]
Rotor	68	122
Nacelle	131	174



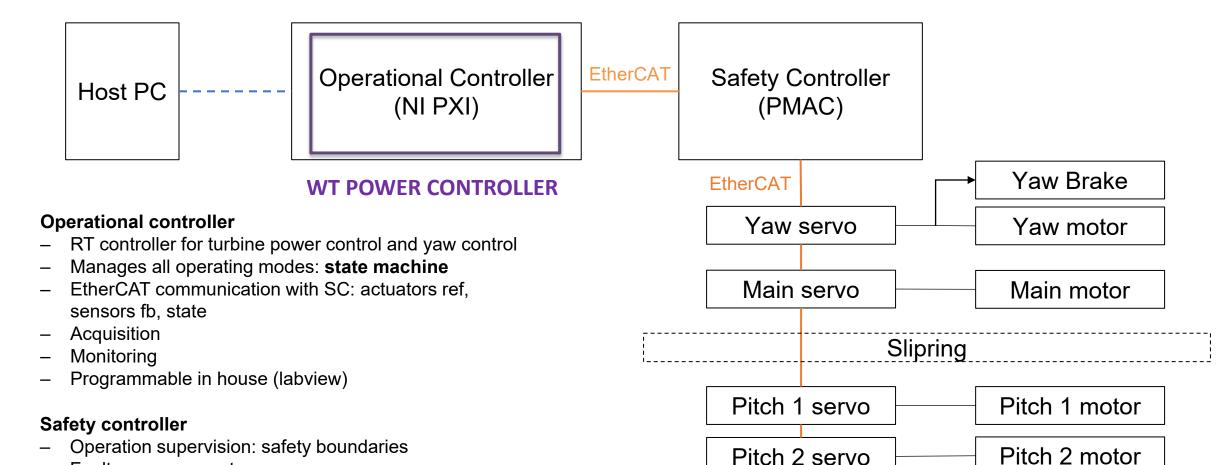
POWER CONTROLLER

- VSVP region based, derived from DTU Basic WE controller / previous works
 - Torque controller
 - Collective pitch controller
- First attempt parameters:
 - Scaled from DTU10MW
 - Adjusted with 1dof drivetrain model to reproduce FS dynamics
 - New aerodynamic gain scheduling factors from aero sensitivity fititng
 - Simulations in FAST/Simulink (turbine-only model)
 - Check floating issue (in FAST aero/hydro model)

YAW CONTROLLER

- Anemometer wind direction feedback
- Misalignment range

For Natural Laboratory tests



Pitch 3 servo

Manages system initialization

Allow manual operations

Faults management

Pitch 3 motor